



SMART BIN FOR WASTE MANAGEMENT IN URBAN AREAS USING IMAGE PROCESSING

¹ Dr. Amitha I C, ²Drishya P K, ³Fathimathul Aifa K P, ⁴Sandra C M, ⁵Sheetal Madhu

¹ Professor, ² Student, ³ Student, ⁴ Student, ⁵ Student

Department of Computer Science and Engineering

St. Thomas College of Engineering and Technology, Kannur, Kerala, India

Abstract : Waste management is an increasingly critical issue in today's society due to its increasing amount. To solve this challenge, we propose a software-based solution inspired by existing solar energy smart sorting boxes. The proposed model aims to classify dry and wet waste using image processing, it also improves the accuracy using deep learning techniques. The software is trained using a dataset of garbage images and its accuracy is evaluated using test images. Real-time implementation can be done by adding a web camera to capture real-time images and classify the waste, and an LED display mounted on the bin will show whether the waste is dry or wet. Although real-time implementation may not be possible at first, this approach is a significant step towards automating waste management processes. The ultimate goal is to promote good management practices and promote a cleaner and more sustainable environment.

IndexTerms – Waste Management, YOLOv5 algorithm, YOLOv5 architecture, Waste Detection and classification, CNN, Documentation.

I. INTRODUCTION

In contemporary society, the escalating volume of waste has made effective waste management an urgent priority. Conventional methods struggle to cope with the scale and diversity of waste generated. However, a significant advancement in artificial intelligence has emerged, offering a new way to approach this challenge. Our innovative waste classification model combines advanced image processing techniques with deep learning to accurately categorize waste into dry and wet types. By leveraging AI algorithms like convolutional neural networks (CNNs), the system automates the classification process with unprecedented precision and efficiency. Unlike manual sorting methods, this AI-driven model streamlines waste management, optimizing resource allocation and environmental impact. It empowers professionals to navigate rising waste volumes effectively, promoting sustainable practices for a cleaner future.

A. PROBLEM STATEMENT

The primary objective is to develop an AI model capable of accurately classifying waste into dry and wet categories using image processing and deep learning techniques. Current methods for managing solid waste often lack precision and efficiency, contributing to environmental challenges and resource depletion. The key challenge is to train the AI model to differentiate between dry and wet waste accurately, optimizing classification performance while minimizing errors. By leveraging advanced image processing and deep learning methodologies, our goal is to enhance waste classification accuracy and support effective waste management practices. This project aims to address the critical need for reliable waste classification systems to promote sustainable environmental stewardship.

II. LITERATURE SURVEY

A literature review serves as an academic document demonstrating understanding and depth of knowledge regarding scholarly literature related to a specific topic, placed within its appropriate context. Typically, it constitutes a section of a dissertation, research project, or comprehensive essay. However, it may also be assigned and evaluated as a standalone task. We picked three articles for the survey: [1] Waste Management using Internet of Things (IoT), [2] Analysis of IoT-enabled solution in Smart Waste Management and [3] Design and Fabrication of Solar-Powered Smart Waste Segregation Trash Bin with Image Processing.

A. Waste Management using Internet of Things(IoT)

This study presents an exploration into waste management, focusing on its evolution and current practices[1]. Waste management involves the treatment and responsible disposal of solid wastes, as well as the exploration of alternative uses for materials traditionally considered as trash.

Over the past century, researchers have delved into waste management, with the last four decades witnessing a surge in waste utilization analysis. Classification of waste management strategies reveals eight major approaches, including reduction and reuse,

recycling, composting, fermentation, and others. These strategies are further divided into various categories, each addressing specific aspects of waste management.

Notably, the reduction and reuse strategy aims to minimize the consumption of disposable materials, thereby reducing waste generation at its source. Technological advancements, particularly in the field of IoT (Internet of Things), offer promising solutions to enhance waste management practices. IoT-enabled systems facilitate real-time monitoring of waste collection routes, optimization of landfill capacities, and data-driven decision-making processes. Waste management is a multifaceted endeavor that requires a comprehensive approach to address environmental concerns effectively[11]. By leveraging historical insights, embracing innovative technologies, and implementing sustainable strategies, stakeholders can work towards achieving efficient and environmentally responsible waste management systems.

B. Analysis of IoT- enabled solution in Smart Waste Management

The Internet of Things (IoT) has garnered broad applicability, extending beyond smart cities to domains like water and waste management. Its impact on daily life and potential to influence user behavior are significant strengths. However, to enhance effectiveness and adoption, it must prioritize energy efficiency and seamless communication across extended areas.

Technologies like Low Power Wide Area Network (LPWAN) with Long Range (LoRa) show promise in this regard. In waste management, various IoT-enabled solutions have been proposed, each with unique strengths and weaknesses requiring refinement. This paper conducts a review of existing IoT solutions in waste management to consolidate the state-of-the-art. The objective is to identify areas for improvement and innovation to ensure effective waste management and a healthy urban environment.

C. Design and Fabrication of Solar-Powered Smart Waste Segregation Trash Bin with Image Processing

The paper introduces a novel strategy to tackle the issue of solid waste management in communities by deploying a solar-powered intelligent waste segregation bin that utilizes image processing technology. The completed implementation of the solar-powered smart waste segregation bin is depicted in Figure 2.1.

The device is engineered to effectively separate four categories of recyclable solid waste materials: plastic, glass, metal, and paper. Leveraging image processing algorithms and a series of sensors, the system autonomously detects, selects, and sorts waste materials deposited into the bin[9]. This not only streamlines the waste segregation process but also enhances the efficiency of recycling initiatives.

A noteworthy aspect of the device is its integration of TensorFlow and Python 3.7, enabling advanced image recognition capabilities. By comparing captured images of solid waste with pre-trained datasets, the system achieves accurate classification, thereby minimizing contamination and maximizing recycling rates. In addition to its sorting capabilities, the smart waste segregation trash bin incorporates an ultrasonic sensor to monitor the amount of solid waste present within the compartment. This real-time monitoring feature facilitates timely waste collection and disposal, optimizing the utilization of waste management resources.

Moreover, the inclusion of a GSM module enables the device to generate SMS notifications to authorized personnel when the bin approaches or reaches its maximum capacity[7]. This proactive alert system ensures efficient waste collection scheduling and prevents overflow incidents, contributing to cleaner and healthier community environments. Furthermore, the device is equipped with a solar panel, harnessing renewable energy to power its operations.

This sustainable energy source not only reduces reliance on conventional power grids but also aligns with environmentally conscious waste management practices. The paper presents promising results from testing, showcasing a 100 percent efficacy in segregating paper and plastics, and notable performance in the segregation of metals and glass. Additionally, the real-time level monitoring trials demonstrated the system's reliability, with all tests yielding favorable outcomes.

The solar-powered intelligent trash bin equipped with image processing technology signifies a major progression in waste management techniques. Its integration of cutting-edge technologies, sustainable energy sources, and proactive monitoring features holds immense promise for enhancing the efficiency, effectiveness, and sustainability of solid waste management in communities. Fig. 1. shows the final design of the solar powered design.

The results of testing, with and without solar panels, are presented in Tables I and II, respectively, offering a comparative analysis of the outcomes[8].

Research Through Innovation



Fig. 1. Solar Powered Design

The results of testing, with and without solar panels, are presented in Tables I and II, respectively, offering a comparative analysis of the outcomes[8].

TABLE I. CAPACITY TO IDENTIFY DIFFERENT KINDS OF RECYCLE WASTE

Recyclable Waste	Trials										Success Rate (%)
	1	2	3	4	5	6	7	8	9	10	
Plastic	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	100
Glass	✓	✗	✗	✓	✓	✗	✗	✗	✓	✓	50
Metallic	✓	✓	✓	✓	✓	✗	✓	✓	✗	✗	70
Paper	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	100

TABLE II. CAPACITY TO IDENTIFY DIFFERENT KINDS OF RECYCLE WASTE USING SOLAR PANEL

Recyclable Waste	Trials										Success Rate (%)
	1	2	3	4	5	6	7	8	9	10	
Plastic	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	100
Glass	✓	✗	✗	✓	✓	✗	✗	✗	✓	✓	50
Metallic	✓	✓	✓	✓	✓	✗	✓	✓	✗	✗	70
Paper	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	100

III. METHODOLOGY

There have been significant advancements in Computer Vision, especially in Object Detection. Object detection involves recognizing and locating objects within images by drawing bounding boxes around them to pinpoint their positions and identifying their respective categories or classes[3]. There are many ways to detect and classify through deep learning such as Visual Geometry Group (VGG), Residual Network (ResNet), YOLOv5, DenseNet, Vision Transformer (ViT) & EfficientNet. While a multitude of architectures exist, YOLOv5 (You Only Look Once, version 5) emerges as a compelling choice for waste classification tasks due to its exceptional blend of speed and accuracy. YOLOv5 offers a spectrum of pretrained models (e.g., YOLOv5s, YOLOv5l) catering to diverse hardware and processing power limitations[4]. This allows us to select a version that aligns perfectly with our specific needs, ensuring optimal performance within your resource constraints.

Unlike some models that need multiple steps, YOLOv5 works in one go. This efficiency stems from its single-stage object detection architecture, which predicts bounding boxes and class probabilities simultaneously in one forward pass through the network. The system takes an image of the waste as an input and it analyzes and simultaneously draws bounding boxes. It identifies objects within the image and creates bounding boxes around them[19]. These boxes indicate the location and size of each waste

item. Classifies the waste, predicts the likelihood of each boxed object belonging to a specific waste category (plastic, metal, etc.) The final output consists of these bounding boxes and their corresponding class labels with probabilities. The sorting system interprets these results, identifying the most likely waste type for each object based on the highest probability class.

IV. PROPOSED METHOD

In response to the escalating challenges of waste management in urban areas, our project introduces an innovative AI-enabled framework for waste detection and segregation[5]. By harnessing advanced image processing techniques and deep learning algorithms, this system aims to accurately classify waste into dry and wet categories, optimizing resource allocation and promoting sustainable waste management practices.

A. Image Acquisition Module

The Image Acquisition Module serves as the foundational component of our waste detection and segregation system. It initiates the process by capturing detailed images of waste items using advanced imaging systems capable of producing high-resolution visuals. These images provide essential data for subsequent analysis and classification of waste materials. The use of high-resolution imaging is critical for capturing fine details and nuances in waste items, enabling accurate identification and classification based on visual attributes. By acquiring images at a detailed level, the system can effectively differentiate between dry and wet waste, laying the groundwork for precise classification and segregation.

B. Image Preprocessing

Image preprocessing is a fundamental step in our waste detection project, aimed at optimizing captured images for accurate analysis by our AI algorithms[22]. This preprocessing stage involves a series of operations to enhance image quality and suitability for subsequent classification tasks: One of the primary goals of image preprocessing is to standardize the images and remove any noise or artifacts that may interfere with the detection process. This is achieved through various techniques, including:

- a) *Image Resizing*: Adjusting image dimensions to a predefined size suitable for input into our AI models, ensuring uniformity and consistency in image processing.
- b) *Image Normalization*: Standardizing brightness, contrast, and color values to reduce variations in image quality and enhance algorithm performance.
- c) *Noise Reduction*: Removing unwanted noise or artifacts from the images, which may result from factors such as camera sensors or environmental conditions. Noise reduction techniques, such as filtering algorithms or denoising methods, help improve the clarity and quality of the images to improve image clarity and facilitate accurate waste classification.
- d) *Image Enhancement*: Enhancing certain features of the images to make them more suitable for detection. This may involve sharpening edges, improving contrast, or enhancing overall clarity using techniques such as edge detection or contrast adjustment.

C. Waste Detection and Classification

The system integrates advanced image processing techniques with the YOLOv5 algorithm to accurately identify and localize waste items within images. Leveraging convolutional layers, our model predicts bounding boxes and confidence scores for detected waste objects, enabling precise localization crucial for environmental monitoring and waste management optimization. Subsequently, our model meticulously analyzes shape, size, and texture attributes to classify waste items into distinct categories, such as distinguishing between dry and wet waste types. This classification capability is foundational for optimizing waste management protocols and promoting sustainable practices to mitigate environmental impact and promote resource efficiency.

a) *Object Detection*: Taking cues from the YOLOv5 algorithm, our AI model employs convolutional layers to identify and localize waste items within preprocessed images[21]. Through convolutional operations and feature extraction, the model predicts bounding boxes and associated confidence scores for each detected waste object, enabling precise localization and classification[20]. This capability is essential for applications like environmental monitoring and waste management optimization. Moreover, the model's adaptability allows for customization and scaling to handle diverse datasets and environmental conditions, ensuring robust performance across various scenarios.

b) *Non-Maximum Suppression (NMS)*: NMS is an essential post-processing step in object detection pipelines, ensuring that the final set of bounding boxes is concise and accurate. By iteratively selecting the highest-confidence boxes and removing overlapping ones, NMS enhances the reliability of object localization, contributing to the overall effectiveness of the detection system. Its efficient implementation is integral to many state-of-the-art object detection algorithms, enabling robust performance in various real-world applications.

c) *Clustering*: In addition to Non-Maximum Suppression (NMS), clustering algorithms can be utilized to group similar bounding boxes together[10]. This approach is beneficial for managing scenarios where multiple instances of the same waste category appear in the image. By clustering these bounding boxes, we can effectively identify and track multiple occurrences of waste items, gaining a comprehensive understanding of their distribution within the waste samples. This aids in improving the accuracy and efficiency of waste classification and segregation processes.

d) *Classification*: Upon completion of the detection phase, our AI model transitions into the classification stage for the identified waste items[15]. During this phase, the model meticulously examines the shape, size, and texture attributes of the waste items,

employing a comparison process with its preestablished knowledge base encompassing various waste categories. This sophisticated analysis allows the system to categorize the waste items into distinct classifications, such as distinguishing between dry and wet waste types. The classification output is of paramount importance as it serves as a foundational element for subsequent analyses and strategic decision-making processes. By accurately classifying waste materials, our system facilitates the optimization of waste management protocols, fostering the implementation of sustainable practices aimed at mitigating environmental impact and promoting resource efficiency

V. PROPOSED SYSTEM DESIGN

The waste detection system utilizes an automated imaging setup to capture detailed images of waste samples[11]. These images undergo preprocessing steps, including noise reduction, contrast enhancement, and image normalization, ensuring clear and consistent data for analysis. Advanced image processing techniques and machine learning algorithms are then employed for waste classification. Trained on large datasets, these algorithms recognize various waste materials with high precision by leveraging features like color, texture, shape, and size. Through systematic pixel analysis and segmentation, the system identifies dry or wet waste based on predefined criteria and reference datasets. Fig.2 illustrates the system architecture, providing a visual depiction of the interconnected components and their interactions, thus elucidating the underlying design and operational framework of the system.

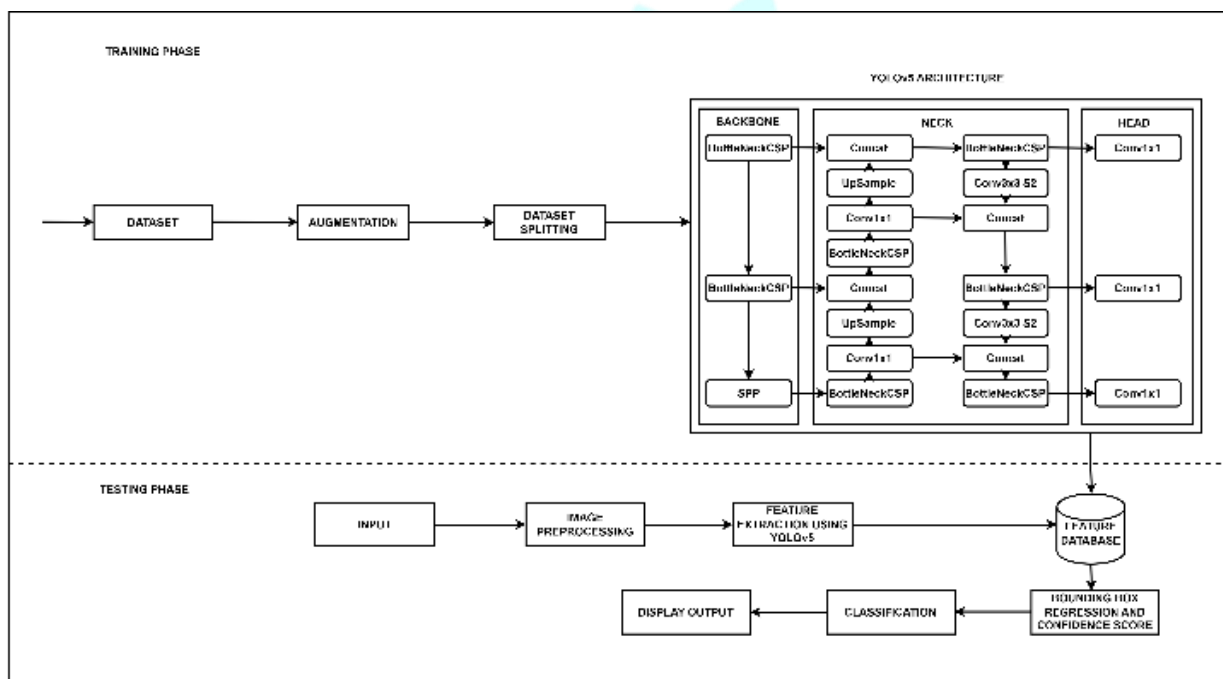


Fig. 2. System Architecture

A. Training Phase

1) *Dataset:* The initial dataset is provided as input which contains images of different types of waste.

2) *Augmentation:* Data augmentation techniques are applied to the dataset to increase its diversity and improve model generalization.

3) *YOLOv5 Architecture:*

a) *Backbone:* The backbone of the architecture consists of multiple **BottleNeckCSP** (CrossStage Partial) blocks, which are a type of residual block used for feature extraction.

b) *Neck:* The neck consists of several components: **Concat**: Concatenation layers that combine feature maps from different stages. **UpSample**: Upsampling layers that increase the spatial resolution of feature maps. **Conv1x1**: 1x1 convolutional layers used for reducing or increasing the number of channels.

c) *Head:* The head consists of the following components: **BottleNeckCSP**: **BottleNeckCSP** blocks for feature extraction. **Conv3x3 S2**: 3x3 convolutional layers with a stride of 2 for downsampling. **Concat**: Concatenation layers that combine feature maps. **Conv1x1**: 1x1 convolutional layers used for reducing or increasing the number of channels.

B. Testing Phase

1) *Input*: A waste sample is provided as input image.

2) *Image Preprocessing*: The acquired images undergo preprocessing to enhance quality, reduce noise, and normalize the data, ensuring optimal input for subsequent stages. 3) *Trained YOLOv5 Model*: The trained YOLOv5 model for waste is tailored specifically for detecting and categorizing waste items within captured images. This model comprises three essential components: the backbone, neck, and head.

a) *Backbone Module*: The backbone serves to capture crucial visual features from preprocessed waste images. It extracts high-level information essential for subsequent classification tasks.

b) *Neck Module*: Following feature extraction, the neck module refines and integrates these features, facilitating multiscale fusion. This process enhances the accuracy of waste item classification by synthesizing diverse visual cues.

c) *Head Module*: The head module plays a pivotal role in determining the precise location and category of detected waste objects. It generates bounding box coordinates and assigns class probabilities, identifying specific waste types within the images. These integrated components work cohesively to enable effective waste detection and classification, providing valuable insights to optimize waste management processes.

4) *Feature Database*: The system extracts features from captured waste images during the training phase and stores them in a dedicated feature database. During the testing phase, features extracted from input waste images are compared against the feature database to facilitate accurate waste classification and identification. This process enables efficient analysis and decision-making in waste sorting and resource allocation.

5) *Bounding box regression and Confidence score*: During waste management tasks, the model predicts bounding boxes around detected waste items within captured images. Additionally, the model assigns confidence scores to these predictions, indicating the system's level of certainty in detecting and classifying the identified waste items. This process plays a crucial role in accurately identifying and localizing waste objects within the images, supporting effective waste sorting and classification efforts.

6) *Waste Classification*: The model classifies detected waste objects into specific categories - dry or wet, based on extracted features[16]. This classification process enables the system to identify and categorize waste items accurately, facilitating streamlined waste sorting and management practices.

VI. RESULT ANALYSIS

The smart waste segregation system has been effectively implemented to detect and classify waste materials as either dry or wet using image processing techniques[14]. Leveraging advanced algorithms, the system analyzes visual cues from captured images to accurately differentiate between dry and wet waste categories. Designed to optimize waste management practices, this system aids in the efficient segregation of dry and wet waste, thereby facilitating improved waste disposal strategies and promoting environmental sustainability.

A. F1 Confidence Curve

In Fig. 3, it displays an F1-Confidence curve, which is a graphical representation used to evaluate the performance of a classification model. It plots the F1 score, a combined measure of precision and recall, against different confidence thresholds for the predicted class probabilities. The curve shows the behavior of the model's performance in distinguishing between two classes, "Dry Waste" and "Wet Waste," as the confidence threshold is varied. The horizontal blue line indicates that at a confidence threshold of 0.148, the model achieves an overall F1 score of 0.52 across all classes. The F1-Confidence curve is calculated by evaluating the classification model's performance metrics (precision, recall, and F1 score) at different confidence thresholds. The F1 score is the harmonic mean of precision and recall, given by: $F1 = 2 * (\text{precision} * \text{recall}) / (\text{precision} + \text{recall})$. The calculated F1 scores are plotted against their corresponding confidence thresholds to create the F1-Confidence curve[12]. By analyzing the curve's trajectory, stakeholders can make informed decisions regarding threshold selection to optimize classification outcomes. Furthermore, the visualization of F1 scores across varying confidence thresholds offers a comprehensive understanding of the model's robustness and its ability to generalize to different confidence levels, enhancing the interpretability and reliability of the classification results.

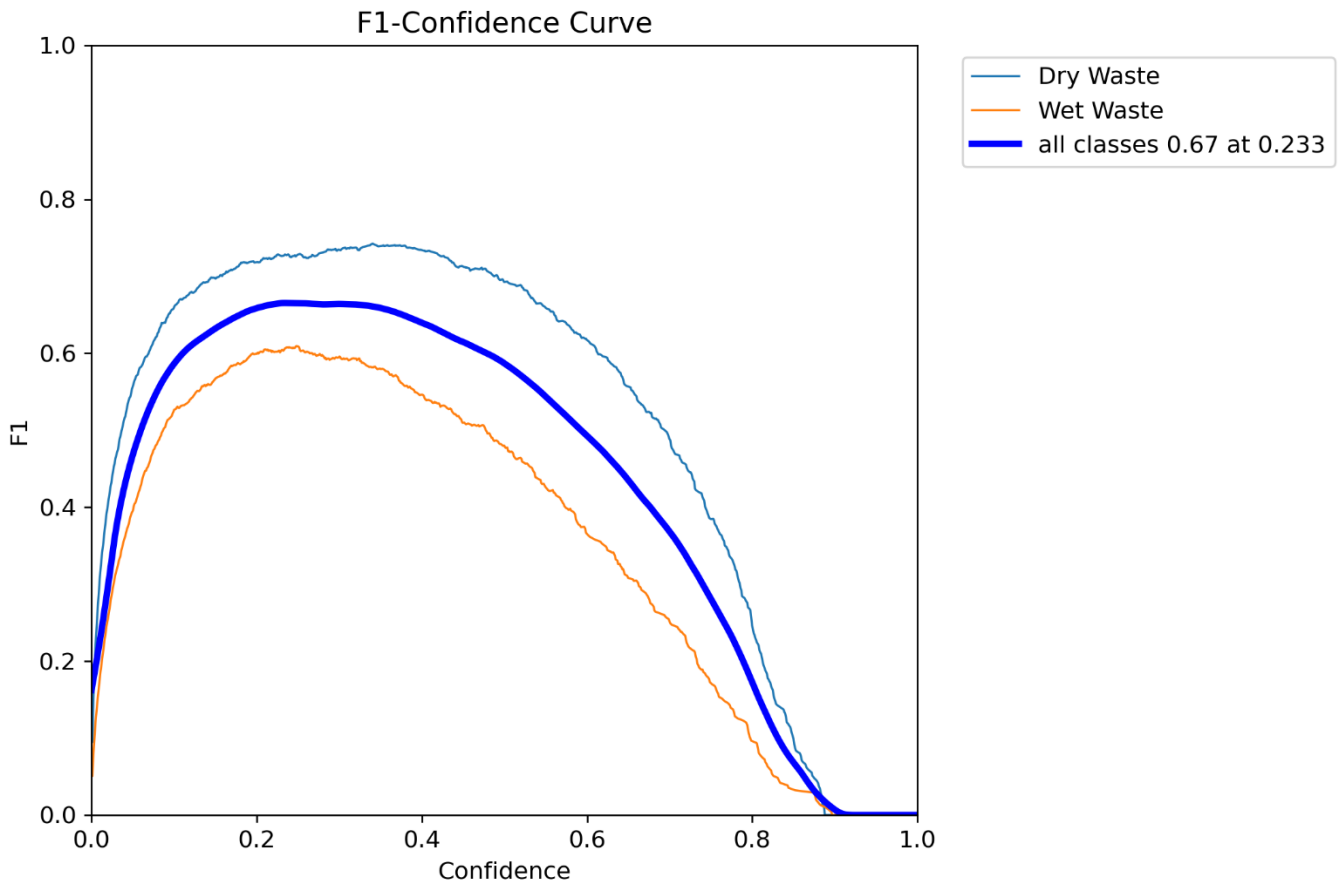


Fig. 3. Confidence Curve

B. Training Loss and Accuracy

Loss and accuracy are two important metrics used to evaluate the performance of a machine learning model during training. Fig.4 shows the training and validation losses for bounding box, object detection, and classes. It also shows the precision and recall matrix

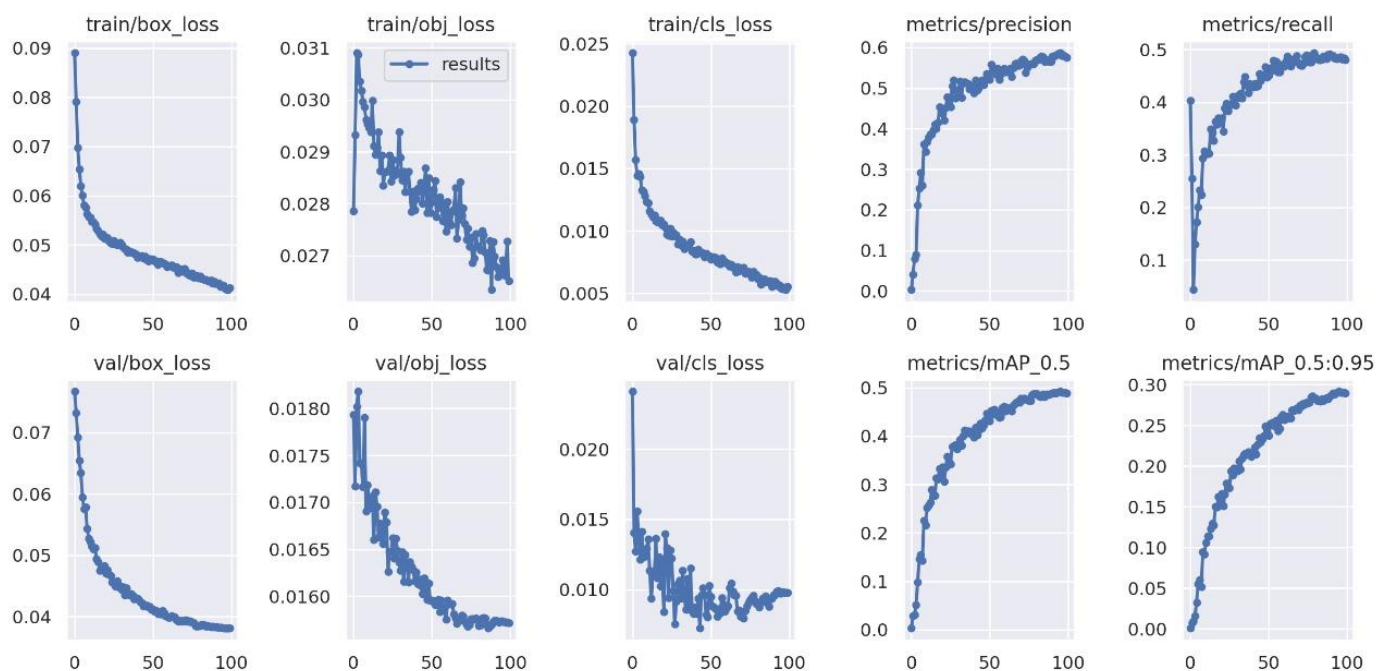


Fig. 4. Training Loss and Accuracy

C. Confusion Matrix

A confusion matrix is a table that shows the performance of a classification model. Fig. 5, shows the confusion matrix of our proposed model. Each row of the matrix represents the actual class of an object, and each column represents the class that the model predicted the object belonged to. The model is classifying images that contain either dry waste, wet waste, or none at all. The top left cell of the matrix shows that the model correctly classified 7 images that actually contained dry waste. The bottom right cell of the matrix shows that the model incorrectly classified 5 images as none, when they actually contained wet waste[17]. The diagonal cells of the confusion matrix show the number of objects that the model classified correctly. In this case, the model performed best at classifying dry waste, and least well at classifying wet waste.

The terms related with confusion matrices are as follows: Accuracy: $(\text{True Positive} + \text{True Negative}) / (\text{Total Samples})$
 Precision: $\text{True Positive} / (\text{True Positive} + \text{False Positive})$ Recall (Sensitivity): $\text{True Positive} / (\text{True Positive} + \text{False Negative})$
 Specificity: $\text{True Negative} / (\text{True Negative} + \text{False Positive})$

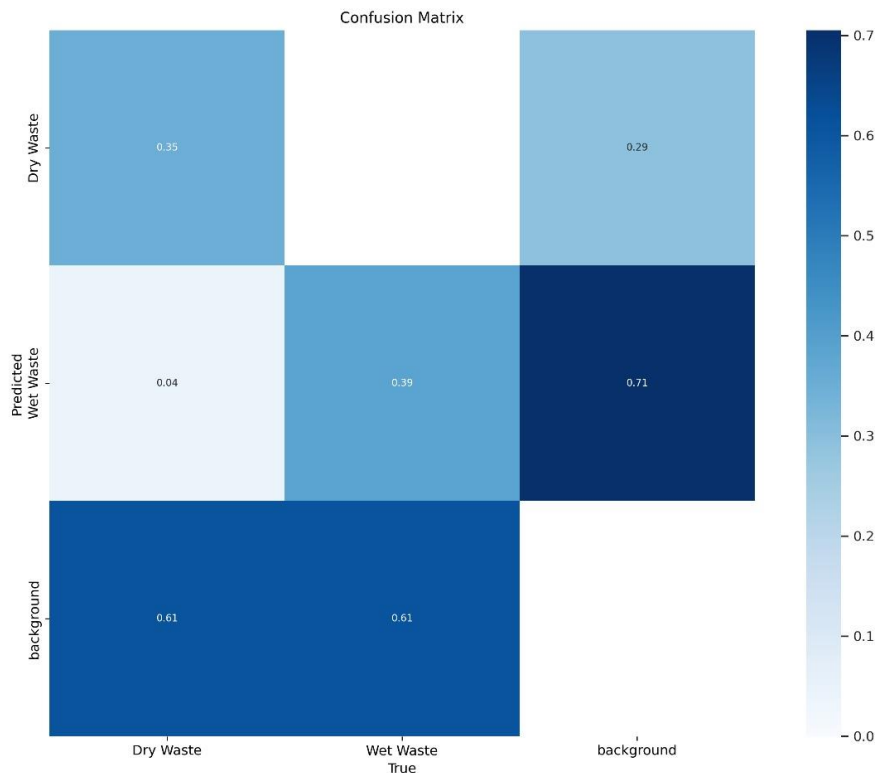


Fig. 5. Confusion Matrix

D. Precision and Recall

Fig.6 shows a precision-recall curve for a YOLOv5 object detection model used in waste detection and segregation. This curve helps us understand how well the model differentiates between different types of waste. The curve in the graph illustrates the trade-off between precision and recall for the model. As the recall of the model increases, it detects more objects and as the precision decreases, the probability that the detected objects are correctly classified reduces.

The text at the bottom of the graph shows the average precision (AP) at 0.5 IoU (Intersection over Union) for each class, and the mean average precision (mAP) across all classes. IoU is a metric used to measure how well a detection box overlaps with the ground truth bounding box for an object.

In the graph you sent, the mAP is 0.493, which means that the model's average precision across all classes is 49.3%.

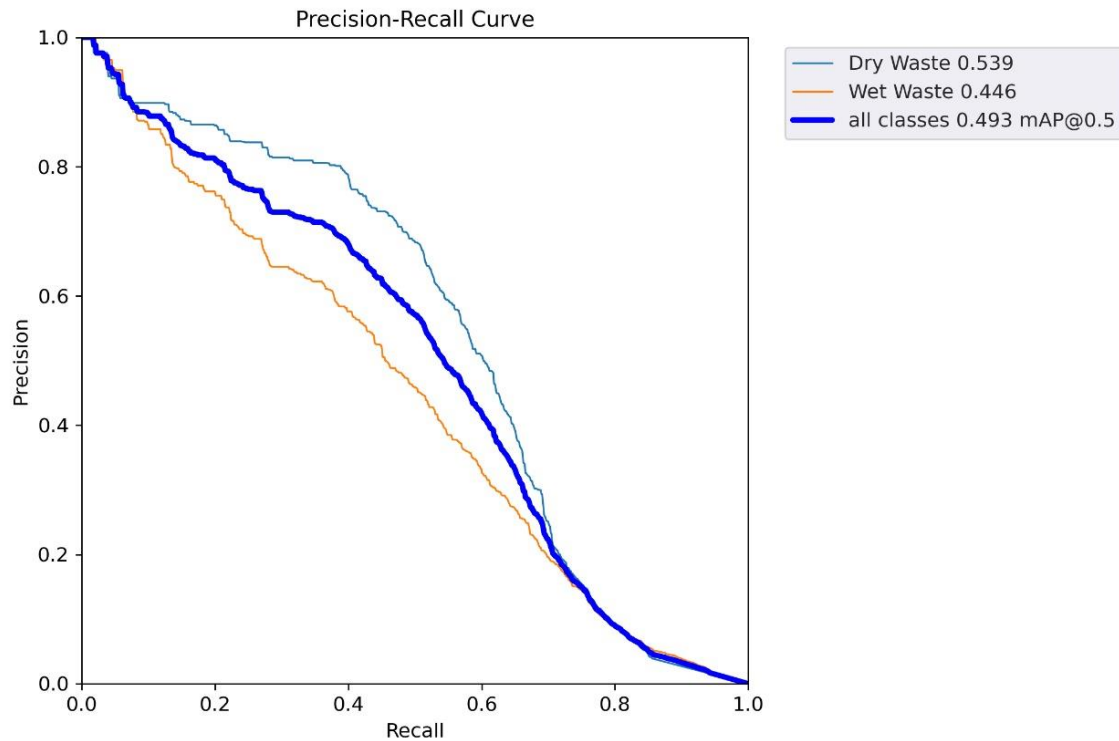


Fig. 6. Precision-Recall Curve

E. Result Comparison Table with Existing System

The table compares the performance of the new model to an existing one for recyclable materials. It shows the success rate achieved by the existing model and the accuracy reported by the proposed model for each material.

a) Both the existing model and the proposed model achieve a 100% success rate/accuracy in detecting plastic. Therefore, there is no difference in accuracy between the two models in the case of plastic.

b) In the case of glass, the existing model achieves a success rate of 70%, while the proposed model achieves an accuracy of 85%. This indicates that the proposed model has a higher accuracy (85%) compared to the existing model (70%) for recycling glass materials.

c) In the case of metals, the existing model achieves a success rate of 50%, while the proposed model achieves an accuracy of 75%. This indicates that the proposed model has a higher accuracy (75%) compared to the existing model (50%) for recycling metal.

d) In the case of paper, both the existing model and the proposed model achieve a 100% success rate/accuracy in recycling paper. Therefore, there is no difference in accuracy between the two models for detecting paper. In general, the proposed model demonstrates improved accuracy compared to the existing model for glass and metal recycling.

TABLE III
RESULT COMPARISON TABLE WITH EXISTING SYSTEM

Recyclable Waste	Success Rate (Existing Model)	Accuracy reported (Proposed Model)
Plastic	100%	100%
Metal	70%	85%
Glass	50%	75%
Paper	100%	100%

VII. CONCLUSION

The implementation of AI-driven waste classification systems represents a pivotal advancement in modern waste management practices, heralding a new era of heightened efficiency and accuracy in waste segregation processes. Through the utilization of cutting-edge algorithms and sophisticated image analysis techniques, these systems empower precise identification of various waste materials, distinguishing between dry and wet components with remarkable accuracy. This capability not only streamlines waste disposal procedures but also plays a pivotal role in promoting environmental sustainability by facilitating optimized waste management strategies. By harnessing the power of artificial intelligence, these innovative systems revolutionize traditional waste management paradigms, paving the way for more effective and sustainable waste handling practices on a global scale. The future of AI-driven waste classification systems holds immense potential for advancing waste management practices, with opportunities to refine accuracy, expand capabilities, and improve usability for various applications in environmental conservation and resource optimization.

REFERENCES

- [1] Tony Rey R. Escalona*, Diana Rose T. Rivera, Ritchard Q. Dizon, Francis Aboy, Bedivere Cabahug, Vic James Mesina, Vee Jay Ramos , "Design and Fabrication of Solar-Powered Smart Waste Segregation Trash Bin with Image Processing", 2022 IEEE 14th International Conference on Humanoid, Nanotechnology, Information Technology, Communication and Control, Environment, and Management (HNICEM)
- [2] D. R. T. Rivera, T. A. Arce, F. R. Abistano, C. J. Bathan and A. A. Palo, "Waste to Energy Technologies using Multi-Criteria Decision Analysis for Municipal Solid Waste Management in Manila City Philippines", 2021 IEEE 13th International Conference on Humanoid Nanotechnology Information Technology Communication and Control Environment and Management (HNICEM), pp. 1-5, 2021.
- [3] H. Zhou, A. Meng, Y. Long, Q. Li and Y. Zhang , "Classification and comparison of municipal solid waste based on thermochemical characteristics", Journal of the Air and Waste Management Association, vol. 64, no. 5, pp. 597-616, 2014.
- [4] M. F. Omar, A. A. A. Termizi, D. Zainal, N. A. Wahap, N. M. Ismail and N. Ahmad, "Implementation of spatial smart waste management system in Malaysia", IOP conference series: Earth and environmental science, vol. 37, no. 1, pp. 12059, 2016.
- [5] S. Mdukaza, B. Isong, N. Dladlu and A. M. Abu-Mahfouz , "Analysis of Iot - enabled solutions in smart waste management", IECON 2018- 44th Annual Conference of the IEEE Industrial Electronics Society, pp. 4639- 4644, 2018.
- [6] H. N. Saha et al., "Waste management using internet of things (iot)", 2017 8th annual industrial automation and electromechanical engineering conference (IEMECON), pp. 359-363, 2017
- [7] L.G.G. Guisansana, J. D. R. Maguyon, C. B. P. Nabing and F. Festijo, "Solid Waste Management: The Enactment of Ecological Solid Waste Management Act of 2000 (RA 9003) in Addressing the Waste Crisis", European Journal of Molecular and Clinical Medicine, vol. 7, no. 02, pp. 2020, 2020.
- [8] J. H. Huh, J. H. Choi and K. Seo, "Smart trash bin model design and future for smart city", Applied Sciences (Switzerland), vol. 11, no. 11, 2021.
- [9] N. K. Soliman and A. F. Moustafa, "Industrial solid waste for heavy metals adsorption features and challenges; a review", Journal of Materials Research and technology, vol. 9, no. 5, pp. 10235-10253, 2020.
- [10] O. Khutsoane, B. Isong and A.M. Abu-Mahfouz, "IoT Devices and Applications based on LoRa/LoRaWAN: A Survey", the 43rd IEEE conference of Industrial Electronic Society, pp. 6107-6112, 2017.
- [11] A. Zanella, S.M., N. Bui, A. Castellani, S.M. Lorenzo Vangelista and M.Zorzi, "Internet of Things for Smart Cities", IEEE Internet of Things Journal, Feb.2014.
- [12] F. Folianto and Y.S.L. Wai Leong Yeow, "Smart bin: Smart Waste Management System", IEEE Tenth International Conference on Intelligent Sensors Sensor Networks and Information Processing (ISSNIP), 2015.
- [13] S.S. Navghane, M.S.K. and D.V.M.R., "IoT based smart garbage and waste collection bin", International Journal of Advanced Research in Electronics and Communication Engineering (IJARECE), vol. 5, no. 5, 2016.
- [14] M.A.B. Abdullah, N. Mohd Yusof, A.Z., M.L. Jidin, S.Z. Rahim, M.E. Abd Rahim, et al., "Smart Garbage Monitoring System for Waste Management", MATEC Web of Conferences, pp. 97, 2017.
- [15] Amitha I. C., N. S. Sreekanth, and N. K. Narayanan, Collaborative Multi-Resolution MSER and Faster RCNN (MRMSER-FRCNN) Model for Improved Object Retrieval of Poor Resolution Images, International Journal of Advanced Computer Science and Applications (IJACSA) Volume 12, Issue 12, pp. 547-554. 2021. DOI:10.14569/IJACSA.2021.0121270.
- [16] Amitha I. C. & N. K. Narayanan, Image Object Retrieval Using Conventional Approaches: A Survey, IJETS Volume V, Issue IX, September, pp. 1-4. 2018.
- [17] Amitha I. C., N. S. Sreekanth, and N. K. Narayanan, Enhanced Object Retrieval by Collaborative Root Scale Invariant Feature Transform and Region-based Convolutional Neural Network (RSIFT-RCNN): communicated to IEEE Transactions on Pattern Analysis and Machine Intelligence.
- [18] Amitha I. C. & N. K. Narayanan, Improved Vehicle Detection and Tracking Using YOLO and CSRT, In Communication and Intelligent Systems, pp. 435-446. Springer, Singapore, DOI: 10.1007/978-981-16- 1089-9_35, 2021.
- [19] Amitha I. C. & N. K. Narayanan, Collaborative MSER and Faster RCNN Model for Retrieval of Objects in Images, In Soft Computing for Problem Solving, pp. 673-682. Springer, Singapore, DOI: 10.1007/978- 981-16-2709-5_51, 2021.
- [20] Amitha, I. C., and N. K. Narayanan. "Object Detection Using YOLO Framework for Intelligent Traffic Monitoring." In Machine Vision and Augmented Intelligence—Theory and Applications, pp. 405-412. Springer, Singapore, DOI: 10.1007/978-981-16-5078-9_34, 2021.

- [21] Amitha I. C. & N. K. Narayanan, Object Retrieval in Images using SIFT and R-CNN, presented in International Conference on Innovative Trends in Information Technology (ICITIIT-20): IIIT Kottayam, DOI: 10.1109/ICITIIT49094.2020.9071557, 2021.
- [22] Amitha I. C., N. S. Sreekanth, and N. K. Narayanan, End-to-end Traffic Monitoring and Management in Real Time Road Traffic communicated to IEEE International conference on Interdisciplinary Approaches in Technology and Management for Social Innovation (IATMSI-2022): ABV-IIITM Gwalior

